R-2000iB™ Series

Basic Description

The FI-2000IB series is FAMUC Relaction tensor-generation, sur-axis, heavy-payless, high-performance tamily of industrial robots. The Fi-2000IB provides higher value through inclusivy-leading performance, reliability and maintainability, and is supported by our extensive senior and parts network.

R-2000 B Series, the Solution for:

- Automotive spot westing and general sessorbly
- General industrial approaches
- Private that branching:
- Plant transfer
- Material semicular
- Dissensing.
- Miscritiria lissostina;

Derror than

- Silve arm and verial passembles reinance starteneous with system periphensis and allow operation in contined spaces.
- Large allowable wind moments and inertias reset a variety of heavy handling challenges.
- Many process attachment points make integration sissier.
- Non-relating towarm simplifies have and cable dressout to protons service life.
- Preven, retable FARUUC sensidrives provide tighest uptime and productivity.
- Langer maintenance intervals equate to lower operating couls.
- Preview resolvantual components retrieve deven time, inchesse mean time between failure (MTBF) and minimus spare part requirements.
- High-performance rectice yields test cycle times and high throughout.
- Whist fluings and tues mounting use identical to the R-2006A, allowing for seamless business? comparisitity.
- R-2006/B can teach all areas of R-2000sA work privilege for easy replacement.

Nate: (FW)carr^(I) and FoundryPRC(^{III}) are registered tradersaries of FANIAC LTD.



Programmes.

Mineral Science of Co.

- Large work envelope with stillty to reach everhead and behind.
- Remarks of recotions.
- Stim arraffer designs.
- PAV replacement on all attents.
- Lack of counterweight increases:
 substates substantials
- Processrapphrodice outsides routed through the aim.
- Wis resolves at reviet.
- Ellerations of indicatable bases steel.
- IPET rated scist/forearts.

Charlest week

- Stiffs average tester TPP and KAMES.[®] execution speed treet previous generation.
- Up to 24 axes on reals services of plus 16 axes on remi-alth part for 40 axes requireme.
- Osubb change amplifier c5 minutes.
- First boot time vi30 separate.
- Two filthernet ports standard.
- USB interface on pariel and PCMCM sixt biterial
- Easy connections to a suriety of I/O, including a number of distributed I/O setuparts.
- (Prindland^{**}), a color, intermet ready teach prendent for even qualer programming and sustem and user interface descor.
- Chall in support for tractions vision applications for sever proefing and robot guidance, without the reset for a PG.

Options:

- Process specific software packages for vertoes applications.
- Web-based saffware tools for remote connectivity, diagnostics and production menitoring.
- FAMUC's (Ptinslon[®] (Integrated)
 Robot Vision) system delivers
 high performance 2-D and 3-D
 machine vision separations with
 FAMUC reliability. Additional
 option for Error Proofing can
 provide integrated vision based
 capabilities to check for product
 completeness before product is
 packaged or further operations
 are performed.
- Founds PRO[®] protection package and two-part egony paint for foundry and hazah environments.
- Standard bookstate for quick robot installation.
- Auxiliary also packages for integration of perpheral servic-servsolled devices and report track setts.
- Adjustable hand stops for JT. 30 and 30.
- Warteus retirot convention cable lengths for flexible outless placement and optional track raised cables.
- Pendant with touch screen for custom HMI applications.
- Monachrome teach pendant.
- Integrated spot yielding utilities.
- Electrically insulated tecephole.



Fanuc Robot Manual Guide

Robert R. Redfield

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Wearable Robotics: Challenges and Trends Juan C. Moreno, Jawad Masood, Urs Schneider, Christophe Maufroy, Jose L. Pons, 2021-07-01 This book reports on advanced topics in the areas of wearable robotics research and practice It focuses on new technologies including neural interfaces soft wearable robots sensors and actuators technologies discussing industrially and medically relevant issues as well as legal and ethical aspects It covers exemplary case studies highlighting challenges related to the implementation of wearable robots for different purposes and describing advanced solutions Based on the 5th International Symposium on Wearable Robotics WeRob2020 and on WearRacon Europe 2020 which were both held online on October 13 16 2020 the book addresses a large audience of academics and professionals working in for the government in the industry and in medical centers as well as end users alike By merging together engineering medical ethical and industrial perspectives it offers a multidisciplinary timely snapshot of the field of wearable technologies From Cogs to Code: The **Evolution of Robotics** Danny Kurt, The story of robotics is a compelling narrative of human ingenuity a testament to our innate desire to create and innovate From the earliest attempts to mimic human actions through simple automatons to the complex AI powered systems of today the evolution of robotics reflects not only our technological progress but also our evolving understanding of ourselves and the world around us This book embarks on a journey through this remarkable history beginning with the ancient dreams and mechanical marvels that laid the groundwork for modern robotics We will explore the fascinating world of early automata revealing how even in antiquity humans sought to create machines capable of simulating life and performing tasks The development of clockwork mechanisms and programmable devices such as the Jacquard loom will be examined highlighting their crucial role in laying the foundations for automated control The narrative then progresses to the post war era charting the birth of modern robotics with the invention of the first industrial robot and the subsequent rise of industrial automation We will delve into the technical advancements that propelled this progress exploring the development of early programming languages sensor technologies and control systems. The integration of artificial intelligence AI into robotics marks another pivotal moment and we will investigate how this convergence has given rise to increasingly autonomous and sophisticated machines The book will also explore the fascinating advancements in robotic locomotion and manipulation from the evolution of robotic arms to the challenges of creating robots capable of walking and navigating complex environments Further we will delve into the crucial role of perception and navigation in robotics examining the techniques used to enable robots to sense their surroundings and interact with the world effectively The diverse applications of robotics across various industries and domains from manufacturing and healthcare to exploration and space will be examined Finally the book will address the important ethical considerations surrounding the rapidly advancing field of robotics discussing the societal implications of automation AI safety and the future of human robot coexistence It is our hope that this comprehensive exploration of the evolution of robotics will provide both a fascinating

historical account and a thoughtful perspective on the future implications of this transformative technology

Manufacturing In The Era Of 4th Industrial Revolution: A World Scientific Reference (In 3 Volumes) ,2021-01-13 The era of the fourth industrial revolution has fundamentally transformed the manufacturing landscape Products are getting increasingly complex and customers expect a higher level of customization and quality Manufacturing in the Era of 4th Industrial Revolution explores three technologies that are the building blocks of the next generation advanced manufacturing The first technology covered in Volume 1 is Additive Manufacturing AM AM has emerged as a very popular manufacturing process The most common form of AM is referred to as three dimensional 3D printing Overall the revolution of additive manufacturing has led to many opportunities in fabricating complex customized and novel products As the number of printable materials increases and AM processes evolve manufacturing capabilities for future engineering systems will expand rapidly resulting in a completely new paradigm for solving a myriad of global problems The second technology is industrial robots which is covered in Volume 2 on Robotics Traditionally industrial robots have been used on mass production lines where the same manufacturing operation is repeated many times Recent advances in human safe industrial robots present an opportunity for creating hybrid work cells where humans and robots can collaborate in close physical proximities This Cobots or collaborative robots has opened up to opportunity for humans and robots to work more closely together Recent advances in artificial intelligence are striving to make industrial robots more agile with the ability to adapt to changing environments and tasks Additionally recent advances in force and tactile sensing enable robots to be used in complex manufacturing tasks These new capabilities are expanding the role of robotics in manufacturing operations and leading to significant growth in the industrial robotics area The third technology covered in Volume 3 is augmented and virtual reality Augmented and virtual reality AR VR technologies are being leveraged by the manufacturing community to improve operations in a wide variety of ways Traditional applications have included operator training and design visualization with more recent applications including interactive design and manufacturing planning human and robot interactions ergonomic analysis information and knowledge capture and manufacturing simulation The advent of low cost solutions in these areas is accepted to accelerate the rate of adoption of these technologies in the manufacturing and related sectors Consisting of chapters by leading experts in the world Manufacturing in the Era of 4th Industrial Revolution provides a reference set for supporting graduate programs in the advanced manufacturing area Innovative Computing 2025, **Volume 2** Hao-Shang Ma, Hwa-Young Jeong, Yu-Wei Chan, Hsuan-Che Yang, 2025-07-22 This book comprises select proceedings of the 7th International Conference on Innovative Computing which was held in Bangkok Thailand Jan 19 23 2025 IC 2025 focusing on cutting edge research carried out in the areas of information technology science and engineering Some of the themes covered in this book are cloud communications and networking high performance computing architecture for secure and interactive IoT satellite communication wearable network and system infrastructure management etc The essays are written by leading international experts making it a valuable resource for researchers and practicing engineers alike Industrial Robots United States. 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